

## WEAK SOLUTIONS OF GRADIENT FLOW OF LANDAU-DE GENNES ENERGY

JINHAE PARK\*

ABSTRACT. Taking into account the flexoelectric effects, we consider a gradient flow of Landau-de Gennes energy which generalizes the Oseen-Frank energy. In this article, we discuss existence of weak solutions of the gradient flow in an appropriate function space.

### 1. Introduction

Molecules in Nematic Liquid Crystals are described by a traceless symmetric second order tensor

$$(1.1) \quad \mathbf{Q} = \int_{\mathbb{S}^2} \ell \otimes \ell f(\ell) d\ell - \frac{1}{3}I,$$

where  $f$  is a probability distribution function satisfying  $f(\ell) = f(-\ell)$  for all  $\ell \in \mathbb{S}^2$ . Shapes of molecules are characterized by three eigenvalues of  $\mathbf{Q}$  and the direction of a molecule is defined by the unit eigenvector whose corresponding eigenvalue has the largest magnitude. The order tensor  $\mathbf{Q}$  is a measure of the local degree of orientational order in liquid crystals. The liquid crystal is said to be uniaxial if two eigenvalues of  $\mathbf{Q}$  are equal, and it is biaxial when  $\mathbf{Q}$  has three distinct eigenvalues. The tensor  $\mathbf{Q}$  is zero in the isotropic phase. Since  $\mathbf{Q}$  is a symmetric matrix, all eigenvalues of  $\mathbf{Q}$  are real and expressed in term of  $\mathbf{Q}$  as [4]

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$$\begin{cases} \lambda_1 = \frac{2\sqrt{\text{tr } \mathbf{Q}^2}}{\sqrt{6}} \cos \alpha, \\ \lambda_2 = \frac{2\sqrt{\text{tr } \mathbf{Q}^2}}{\sqrt{6}} \left( -\frac{1}{2} \cos \alpha - \frac{\sqrt{3}}{2} \sin \alpha \right), \\ \lambda_3 = \frac{2\sqrt{\text{tr } \mathbf{Q}^2}}{\sqrt{6}} \left( -\frac{1}{2} \cos \alpha + \frac{\sqrt{3}}{2} \sin \alpha \right), \end{cases}$$

where

$$\cos(3\alpha) = -\frac{\sqrt{6}\text{tr } \mathbf{Q}^3}{\text{tr } \mathbf{Q}^2 \sqrt{\text{tr } \mathbf{Q}^2}}, \quad \sin(3\alpha) = \sqrt{1 - \frac{6(\text{tr } \mathbf{Q}^3)^2}{(\text{tr } \mathbf{Q}^2)^3}}, \quad \alpha \in \left[ 0, \frac{\pi}{3} \right].$$

It follows from  $\text{tr } \mathbf{Q} = 0$  and  $\mathbf{Q} = \mathbf{Q}^T$  that  $6(\text{tr } \mathbf{Q}^3)^2 \leq (\text{tr } \mathbf{Q}^2)^3$ . Moreover,  $\mathbf{Q}$  has two distinct eigenvalues if and only if  $6(\text{tr } \mathbf{Q}^3)^2 = (\text{tr } \mathbf{Q}^2)^3$ . From (1.1), it can be easily seen that  $-\frac{1}{3} \leq \lambda_i \leq \frac{2}{3}$  for  $i = 1, 2, 3$ . It then follows that  $\text{tr } \mathbf{Q}^2 \leq \frac{1}{6}$ .

If  $\mathbf{Q}$  is expressed by

$$\mathbf{Q} = S_1 \left( \mathbf{m} \otimes \mathbf{m} - \frac{1}{3} \mathbf{I} \right) + S_2 \left( \mathbf{n} \otimes \mathbf{n} - \frac{1}{3} \mathbf{I} \right),$$

where  $\{\mathbf{m}, \mathbf{n}, \mathbf{m} \times \mathbf{n}\}$  is an orthonormal basis for  $\mathbf{R}^3$  consisting of unit eigenvectors of  $\mathbf{Q}$ , then the eigenvalues are

$$\frac{1}{3}(2S_1 - S_2), \quad -\frac{1}{3}(S_1 + S_2), \quad \frac{1}{3}(2S_2 - S_1).$$

In the Landau-de Gennes theory, neglecting the higher derivatives and powers of  $\mathbf{Q}$  the free energy density  $\mathcal{F}$  for nematic liquid crystals is given by

$$\begin{aligned} \mathcal{F}(\mathbf{Q}, \nabla \mathbf{Q}) \\ = \frac{1}{2} (L_1 Q_{\alpha\beta,\gamma} Q_{\alpha\beta,\gamma} + L_2 Q_{\alpha\beta,\beta} Q_{\alpha\gamma,\gamma} + L_3 Q_{\alpha\beta,\gamma} Q_{\alpha\gamma,\beta}) + f_{bulk}(\mathbf{Q}), \end{aligned}$$

where

$$f_{bulk}(\mathbf{Q}) = \frac{A}{2} \text{tr } \mathbf{Q}^2 - \frac{B}{3} \text{tr } \mathbf{Q}^3 + \frac{C}{4} (\text{tr } \mathbf{Q}^2)^2.$$

The bulk energy  $f_{bulk}$  is a potential function for uniaxial nematic liquid crystals, meaning that  $f_{bulk}$  favors molecules to be uniaxial. In order to study biaxial liquid crystals, we need to add higher powers of  $\mathbf{Q}$  to  $f_{bulk}$ . In liquid crystals, there exists a polarization induced by a splay and bending distortion [2, 1]. Such a polarization is called flexoelectric polarization which is analogous to piezoelectric polarization in solids. The flexoelectric polarization can be written in terms of  $\mathbf{Q}$  as

$$\mathbf{P}^f = (P_1, P_2, P_3),$$

$$P_i = \epsilon_3 Q_{ij,j} + \epsilon_4 Q_{jk} Q_{ij,k} + \epsilon_5 Q_{ij} Q_{jk,k} + \text{higher order.}$$

Due to the appearance of the flexoelectric polarization, the following electrostatic equations (Maxwell's equations) will be taken into account in the system

$$(1.2) \quad \nabla \cdot (\epsilon(\mathbf{Q})\mathbf{E}) = -\nabla \cdot \mathbf{P}^f, \quad \nabla \times \mathbf{E} = 0,$$

where  $\epsilon(\mathbf{Q})$  is the dielectric permittivity tensor given by

$$\epsilon(\mathbf{Q}) = \epsilon_0 \mathbf{I} + \epsilon_1 \mathbf{Q} + \epsilon_2 \mathbf{Q}^2.$$

Hence the electrostatic energy is

$$f_{elec} = -\frac{1}{2}(\epsilon(\mathbf{Q})\mathbf{E}) \cdot \mathbf{E} - \mathbf{P}^f \cdot \mathbf{E}.$$

If we let

$$\mathbf{Q} = \frac{3}{2}S(\mathbf{n} \otimes \mathbf{n} - \frac{1}{3}\mathbf{I}),$$

then

$$\epsilon(\mathbf{Q})\mathbf{E} \cdot \mathbf{E} = \left(\epsilon_0 - \frac{\epsilon_1}{2}S + \frac{\epsilon_2}{4}S^2\right) |\mathbf{E}|^2 + \frac{3}{2}S \left(\epsilon_1 + \frac{\epsilon_2}{2}S\right) (\mathbf{n} \cdot \mathbf{E})^2,$$

$$\mathbf{P}^f = e_{11}(\nabla \cdot \mathbf{n})\mathbf{n} + e_{33}\mathbf{n} \times \nabla \times \mathbf{n},$$

$$e_{11} = \frac{3}{2}\epsilon_3 S + \frac{3}{4}(2\epsilon_5 - \epsilon_4)S^2, \quad e_{33} = \frac{3}{2}\epsilon_3 S + \frac{3}{4}(2\epsilon_4 - \epsilon_5)S^2.$$

Then the permittivity  $\epsilon_{\perp}$  and dielectric anisotropic constant  $\epsilon_a$  are defined by

$$\epsilon_{\perp} = \epsilon_0 - \frac{\epsilon_1}{2}S + \frac{\epsilon_2}{4}S^2, \quad \epsilon_a = \frac{3}{2}S \left(\epsilon_1 + \frac{\epsilon_2}{2}S\right).$$

Now, since eigenvalues of  $\mathbf{Q}$  are in between  $-\frac{1}{3}$  and  $\frac{2}{3}$ , we impose the following condition for strong ellipticity of (1.2)

$$3\epsilon_0 > \epsilon_1 \quad \text{if } \epsilon_1 > 0, \quad \text{and} \quad 3\epsilon_0 > -2\epsilon_1 \quad \text{if } \epsilon_1 \leq 0.$$

Since some material can have  $\epsilon_1 > 0$  and  $S > 0$ , we have to include  $\epsilon_2$ -term in order to satisfy solvability condition  $\epsilon_{\perp} > |\epsilon_a|$ . For a sake of simplicity, we take  $\epsilon_4 = \epsilon_5 = 0$  so that equations (1.2) become

$$(1.3) \quad \nabla \cdot [(\epsilon_0 \mathbf{I} + \epsilon_1 \mathbf{Q} + \epsilon_2 \mathbf{Q}^2) \nabla \varphi] = -\epsilon_3 \nabla \cdot (\nabla \cdot \mathbf{Q}),$$

where  $\nabla \cdot \mathbf{Q} = Q_{1j,j}\mathbf{e}_x + Q_{2j,j}\mathbf{e}_y + Q_{3j,j}\mathbf{e}_z$ ,  $\{\mathbf{e}_x, \mathbf{e}_y, \mathbf{e}_z\}$  is a set of unit vectors in  $x, y, z$  axes respectively, and  $\varphi$  is an electric potential function, i.e.  $\mathbf{E} = \nabla \varphi$ .

By Maxwell's equation, the electrostatic energy functional can be written as

$$\int_{\Omega} f_{elec} dx = -\frac{1}{2} \int_{\Omega} (\nabla \cdot \mathbf{Q}) \cdot \nabla \varphi dx$$

The total energy functional  $\mathcal{E}$  is

$$\begin{aligned} &\mathcal{E}(\mathbf{Q}, \varphi) \\ &= \int_{\Omega} \left\{ \frac{1}{2} L |\nabla \mathbf{Q}|^2 + \frac{A}{2} \text{tr } \mathbf{Q}^2 - \frac{B}{3} \text{tr } \mathbf{Q}^3 + \frac{C}{4} (\text{tr } \mathbf{Q}^2)^2 - \frac{1}{2} \epsilon_3 (\nabla \cdot \mathbf{Q}) \cdot \nabla \varphi \right\} dx. \end{aligned}$$

In the absence of a flow, equations for dynamic problems are

$$(1.4) \quad \begin{aligned} \frac{\partial \mathbf{Q}}{\partial t} &= L \Delta \mathbf{Q} - A \mathbf{Q} + B \left( \mathbf{Q}^2 - \frac{\text{tr } \mathbf{Q}^2}{3} \mathbf{I} \right) - C (\text{tr } \mathbf{Q}^2) \mathbf{Q} \\ &\quad - \frac{1}{2} \epsilon_3 \left( \nabla^2 \varphi - \frac{1}{3} \Delta \varphi \mathbf{I} \right) \text{ in } \Omega. \end{aligned}$$

subject to

$$(1.5) \quad \nabla \cdot (\epsilon(\mathbf{Q}) \nabla \varphi) = -\epsilon_3 \nabla \cdot (\nabla \cdot \mathbf{Q}) \quad \text{in } \Omega,$$

and boundary conditions

$$(1.6) \quad \begin{cases} \frac{\partial \mathbf{Q}(x,t)}{\partial \nu} = \mathbf{0} & \text{on } \Gamma, & \mathbf{Q}(x,t) = \mathbf{Q}_1(x) & \text{on } \partial\Omega \setminus \Gamma, \\ \varphi(x,t) = \varphi_0(x) & \text{on } \Gamma, & \frac{\partial \varphi(x,t)}{\partial \nu} = 0 & \text{on } \partial\Omega \setminus \Gamma, \end{cases}$$

where  $\mathbf{Q}_1$  is fixed.

From now on, we study existence of weak solutions of the system (1.4)-(1.5) with the boundary conditions (1.6).

### 2. A priori estimates

In this section, we study a priori estimates for solutions which will be used in the next section. Let us introduce

$$\begin{aligned} W^{1,2}(\Omega; \mathcal{S}_0) &= \{ \mathbf{Q} : \|\mathbf{Q}\|_{L^2(\Omega)} + \|\nabla \mathbf{Q}\|_{L^2(\Omega)} < \infty, \mathbf{Q} : \Omega \rightarrow \mathcal{S}_0 \}, \\ H^1_{\Gamma}(\Omega) &= \left\{ \psi \in H^1(\Omega) : \psi = 0 \text{ on } \Gamma, \frac{\partial \psi}{\partial \nu} = 0 \text{ on } \partial\Omega \setminus \Gamma \right\}. \end{aligned}$$

For any  $p > 0$ , and  $t > 0$ , we denote by  $L^p(0, t; \mathcal{V})$  the space of all functions  $\mathbf{Q} : (0, t) \rightarrow \mathcal{V}$  such that

$$\int_0^t \|\mathbf{Q}\|_{\mathcal{V}} dt < \infty,$$

where  $\mathcal{V}$  is a function space equipped with its norm  $\|\cdot\|_{\mathcal{V}}$ . We look for a weak solution of the system (1.4),(1.5), and (1.6). In other words, the problem is to find  $\mathbf{Q} \in L^2(0, T; W^{1,2}(\Omega; \mathcal{S}_0))$  and  $\varphi \in L^2(0, T; H^1(\Omega))$  satisfying

$$(2.1) \quad \left\{ \begin{array}{l} \int_{\Omega} \left\{ \left( \frac{\partial \mathbf{Q}}{\partial t} + L \nabla \mathbf{Q} + A \mathbf{Q} - B \mathbf{Q}^2 + C(\text{tr } \mathbf{Q}^2) \mathbf{Q} \right) \cdot \mathbf{T} \right\} dx \\ \qquad \qquad \qquad = \frac{1}{2} \epsilon_3 \int_{\Omega} \nabla \varphi \cdot (\nabla \cdot \mathbf{T}) dx, \\ \int_{\Omega} (\epsilon(\mathbf{Q}) \nabla \varphi) \cdot \nabla \psi dx = \int_{\Gamma} (\epsilon(\mathbf{Q}_1) \nabla \varphi_0 \cdot \boldsymbol{\nu}) \psi dA - \int_{\Omega} (\nabla \cdot \mathbf{Q}) \cdot \nabla \psi dx, \\ \frac{\partial \mathbf{Q}(x,t)}{\partial \boldsymbol{\nu}} = \mathbf{0} \quad \text{on } \Gamma, \quad \mathbf{Q}(x,t) = \mathbf{Q}_1(x) \quad \text{on } \partial\Omega \setminus \Gamma, \\ \varphi(x,t) = \varphi_0(x) \quad \text{on } \Gamma, \quad \frac{\partial \varphi(x,t)}{\partial \boldsymbol{\nu}} = 0 \quad \text{on } \partial\Omega \setminus \Gamma, \end{array} \right.$$

for all  $\mathbf{T} \in W^{1,2}(\Omega; \mathcal{S}_0)$  and  $\psi \in H^1_0(\Omega)$ .

LEMMA 2.1. *Let  $(\mathbf{Q}, \varphi)$  be a solution pair of functions to (1.4),(1.5), and (1.6). Then*

$$\mathbf{Q} \in L^2(0, T; W^{1,2}(\Omega; \mathcal{S}_0)) \cap L^4(0, T; L^4(\Omega; \mathcal{S}_0)), \quad \varphi \in L^2(0, T; H^1(\Omega)).$$

*Proof.* Let  $(\mathbf{Q}, \varphi)$  be a solution pair of functions to (1.4),(1.5), and (1.6). Multiplying each equation in (1.4) by  $Q_{ij}$  and integrating by parts followed by summing up, we obtain

$$(2.2) \quad \begin{aligned} \frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 dx + \int_{\Omega} (L|\nabla \mathbf{Q}|^2 + A \text{tr } \mathbf{Q}^2 - B \text{tr } \mathbf{Q}^3 + C(\text{tr } \mathbf{Q}^2)^2) dx \\ = \frac{1}{2} \epsilon_1 \int_{\Omega} \nabla \varphi \cdot (\nabla \cdot \mathbf{Q}) dx. \end{aligned}$$

Similarly, multiplying (1.5) by  $\varphi$  and integrating by parts yield

$$(2.3) \quad \int_{\Omega} (\epsilon(\mathbf{Q}) \nabla \varphi) \cdot \nabla \varphi dx = -\epsilon_3 \int_{\Omega} (\nabla \cdot \mathbf{Q}) \cdot \nabla \varphi dx.$$

Combining (2.2) with (2.3) we obtain

$$(2.4) \quad \begin{aligned} \frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 dx + \int_{\Omega} \left( L|\nabla \mathbf{Q}|^2 + C(\text{tr } \mathbf{Q}^2)^2 + \frac{1}{2} (\epsilon(\mathbf{Q}) \nabla \varphi) \cdot \nabla \varphi \right) dx \\ = \int_{\Omega} (-A \text{tr } \mathbf{Q}^2 + B \text{tr } \mathbf{Q}^3) dx. \end{aligned}$$

By Hölder inequality, choose  $\eta > 0$  such that  $C - B\eta^2 > 0$  and

$$(2.5) \quad \int_{\Omega} \text{tr } \mathbf{Q}^3 dx \leq \int_{\Omega} \left\{ \frac{1}{\eta^2} \text{tr } \mathbf{Q}^2 + \eta^2 (\text{tr } \mathbf{Q}^2)^2 \right\} dx.$$

It follows from (2.4) and (2.5) that

$$(2.6) \quad \frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 dx + \int_{\Omega} \left( L|\nabla \mathbf{Q}|^2 + \tilde{C}(\text{tr } \mathbf{Q}^2)^2 + \frac{1}{2} (\epsilon(\mathbf{Q})\nabla\varphi) \cdot \nabla\varphi \right) dx \leq \mathcal{M}\|\mathbf{Q}\|_{L^2} + \mathcal{D},$$

where  $\tilde{C} = C - \frac{1}{\eta^2}$ , and  $\mathcal{M} = -A + \frac{B}{\eta^2}$ . Hence we get

$$\frac{d}{dt} \|\mathbf{Q}\|_{L^2}^2 \leq \mathcal{M}\|\mathbf{Q}\|_{L^2}^2 + \mathcal{D},$$

and Grownwall's inequality leads us to have

$$(2.7) \quad \|\mathbf{Q}(t)\|_{L^2}^2 \leq \|\mathbf{Q}(0)\|_{L^2}^2 e^{\mathcal{M}t} + \frac{\mathcal{D}}{\mathcal{M}} (e^{\mathcal{M}t} - 1).$$

This implies that

$$\sup_{0 \leq t \leq T} \|\mathbf{Q}(t)\|_{L^2}^2 \leq \|\mathbf{Q}(0)\|_{L^2}^2 e^{\mathcal{M}T} + \frac{\mathcal{D}}{\mathcal{M}} (e^{\mathcal{M}T} - 1),$$

and integrating (2.6) with respect to  $t$  yields

$$\int_0^T \int_{\Omega} \left( L|\nabla \mathbf{Q}|^2 + \tilde{C}(\text{tr } \mathbf{Q}^2)^2 + \frac{1}{2} (\epsilon(\mathbf{Q})\nabla\varphi) \cdot \nabla\varphi \right) dx dt < \infty.$$

Since  $(\epsilon(\mathbf{Q})\nabla\varphi) \cdot \nabla\varphi \geq \lambda\|\nabla\varphi\|^2$  for some  $\lambda > 0$ , by Poincare inequality we have

$$\mathbf{Q} \in L^2(0, T; W^{1,2}(\Omega; \mathcal{S}_0)) \cap L^4(0, T; L^4(\Omega; \mathcal{S}_0)), \varphi \in L^2(0, T; H^1(\Omega)).$$

□

### 3. Existence of weak solution

**THEOREM 3.1.** *For any given  $T > 0$ ,  $\mathbf{Q}_0 \in L^2(\Omega; \mathcal{S}_0)$ , there exists a solution pair  $(\mathbf{Q}, \varphi)$  to (2.1) such that  $\mathbf{Q} \in L^2(0, T; W^{1,2}(\Omega; \mathcal{S}_0))$  and  $\varphi \in L^2(0, T; H^1(\Omega))$ . Moreover, if  $\mathbf{Q}_0 \in W^{1,2}(\Omega; \mathcal{S}_0)$ , then*

$$\mathbf{Q} \in C(0, T; W^{1,2}(\Omega; \mathcal{S}_0)) \cap L^4(0, T; L^4(\Omega; \mathcal{S}_0)), \frac{\partial \mathbf{Q}}{\partial t} \in L^2(0, T; L^2(\Omega; \mathcal{S}_0)).$$

*Proof.* We use the Galerkin Method [6] to obtain a weak solution  $(\mathbf{Q}, \varphi)$  to (2.1). We first approximate  $W^{1,2}(\Omega, \mathcal{S}_0)$  and  $H^1(\Omega)$  by increasing sequences of finite dimensional subspaces  $\mathcal{X}^m \subset W^{1,2}(\Omega, \mathcal{S}_0)$ , and  $\mathcal{Y}^m \subset H^1(\Omega)$  such that

$$\cup_{m=1}^{\infty} \mathcal{X}^m = W^{1,2}(\Omega, \mathcal{S}_0), \quad \cup_{m=1}^{\infty} \mathcal{Y}^m = H^1(\Omega).$$

For each  $m \in \mathbb{N}$ , let  $\{\mathbf{x}_i\}_{i=1}^m$  and  $\{y_i\}_{i=1}^m$  be orthonormal bases for  $\mathcal{X}^m$  and  $\mathcal{Y}^m$ , respectively. We first seek a solution pair  $(\mathbf{Q}^m, \varphi^m)$  in  $\mathcal{X}^m \times \mathcal{Y}^m$  in the form

$$\mathbf{Q}^m(x, t) = \sum_{i=1}^m p_i(t)\mathbf{x}_i(x), \quad \varphi^m(x, t) = \sum_{i=1}^m q_i(t)y_i(x).$$

Substituting  $(\mathbf{Q}^m, \varphi^m)$  for  $(\mathbf{Q}, \varphi)$  in (2.1), and taking  $\mathbf{T} = \mathbf{x}_j, \psi = y_k$ , we obtain a system of nonlinear ordinary differential equations for  $\{p_i(t), q_i(t)\}_{i=1}^m$ . It follows from the standard theory of ODEs that the new system has a unique solution on some interval  $[0, t_m] \subset [0, T]$ . By lemma 2.1, we know that

$$\sup_{0 \leq t \leq T} \{ \|\mathbf{Q}^m(t)\|_{L^2}, \|\varphi^m(t)\|_{L^2} \} < \infty.$$

We extend  $\mathbf{Q}^m, \varphi^m$  to the interval  $[0, T]$  by the standard continuation method [3, 6]. Apply Lemma 2.1 again to show that  $\{\mathbf{Q}^m\}_{m \in \mathbb{N}}$  is bounded in  $L^2(0, T; W^{1,2}(\Omega; \mathcal{S}_0)) \cap L^4(0, T; L^4(\Omega; \mathcal{S}_0))$ , and  $\{\varphi^m\}_{m \in \mathbb{N}}$  is bounded in  $L^2(0, T; H^1(\Omega))$ . Note that  $\{(\text{tr}(\mathbf{Q}^m)^2)\mathbf{Q}^m\}_{m \in \mathbb{N}}$  is bounded in  $L^{\frac{4}{3}}((0, T) \times \Omega)$ .

We can extract a subsequence (not relabeled)  $\{(\mathbf{Q}^m, \varphi^m)\}_{m \in \mathbb{N}}$  such that

$$(3.1) \quad \begin{cases} \mathbf{Q}^m \rightharpoonup \bar{\mathbf{Q}} \text{ weakly in } L^2(0, T; W^{1,2}(\Omega; \mathcal{S}_0)), \\ \mathbf{Q}^m \rightharpoonup \bar{\mathbf{Q}} \text{ weakly in } L^4(0, T; L^4(\Omega; \mathcal{S}_0)), \\ (\text{tr}(\mathbf{Q}^m)^2)\mathbf{Q}^m \rightharpoonup \mathbf{P} \text{ weakly in } L^{\frac{4}{3}}((0, T) \times \Omega), \\ \varphi^m \rightharpoonup \bar{\varphi} \text{ weakly in } L^2(0, T; H^1(\Omega)). \end{cases}$$

Using the Sobolev imbedding  $W^{1,2} \subset L^4$ [5], we obtain imbeddings

$$L^4(0, T; W^{1,2}(\Omega; \mathcal{S}_0)) \hookrightarrow L^4((0, T) \times \Omega; \mathcal{S}_0), \\ L^{\frac{4}{3}}((0, T) \times \Omega; \mathcal{S}_0) \hookrightarrow L^{\frac{4}{3}}(0, T; [W^{1,2}(\Omega; \mathcal{S}_0)]').$$

It follows that  $\left\{ \frac{\partial \mathbf{Q}^m}{\partial t} \right\}_{m \in \mathbb{N}}$  is bounded in  $L^{\frac{4}{3}}(0, T; [W^{1,2}(\Omega; \mathcal{S}_0)]')$ . Since  $\{\mathbf{Q}^m\}_{m \in \mathbb{N}}$  is bounded in  $L^2(0, T; W^{1,2}(\Omega; \mathcal{S}_0))$ , Aubin's compactness shows that

$$\mathbf{Q}^m \rightarrow \bar{\mathbf{Q}} \text{ strongly in } L^2(0, T; L^2(\Omega; \mathcal{S}_0)).$$

This concludes that  $(\text{tr} \bar{\mathbf{Q}}^2)\bar{\mathbf{Q}} = \mathbf{P}$ , and therefore  $(\bar{\mathbf{Q}}, \bar{\varphi})$  is a weak solution pair. □

**COROLLARY 1.** *There exists a weak solution pair  $(\mathbf{Q}, \varphi)$  which belongs to  $L^2(0, \infty; W^{1,2}(\Omega; \mathcal{S}_0) \times L^2(0, \infty; H^1(\Omega)))$  to (1.4), (1.5), and (1.6).*

*Proof.* As in the proof of lemma 2.1, multiplying (1.4),(1.5) by  $\mathbf{Q}$  and  $\varphi$  followed by integration by parts we obtain

$$(3.2) \quad \int_{\Omega} \left( L|\nabla\mathbf{Q}|^2 + A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C(\operatorname{tr} \mathbf{Q}^2)^2 + \frac{1}{2} (\epsilon(\mathbf{Q})\nabla\varphi) \cdot \nabla\varphi \right) dx + \frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 dx = 0$$

Since  $C > 0$ , there exists  $\mathcal{D}$  such that  $A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C(\operatorname{tr} \mathbf{Q}^2)^2 \geq -\mathcal{D}$ . It follows from (3.2) and the Poincare inequality that

$$\frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 dx + \mathcal{M} \int_{\Omega} |\mathbf{Q}|^2 dx \leq \mathcal{D}|\Omega|,$$

where  $\mathcal{M} = \frac{L}{\mathcal{K}} > 0$  with the Poincare constant  $\mathcal{K}$ . By Grownwall's inequality we have

$$\|\mathbf{Q}(t)\|_{L^2} \leq \|\mathbf{Q}(0)\|_{L^2} e^{-\mathcal{M}t} + \frac{\mathcal{D}|\Omega|}{\mathcal{M}} (1 - e^{-\mathcal{M}t}).$$

Therefore  $\sup_{0 \leq t < \infty} \|\mathbf{Q}(t)\|_{L^2} \leq \frac{\mathcal{D}|\Omega|}{\mathcal{M}}$  and the proof is complete.  $\square$

Next, we prove that such a weak solution is unique and it converges to an equilibrium solution of the energy functional  $\mathcal{E}$ .

**THEOREM 3.2.** *If  $\epsilon_1 = \epsilon_2 = 0$  in (1.5), then there exists a unique weak solution to (1.4),(1.5), and (1.6).*

*Proof.* Let  $(\mathbf{Q}_1, \varphi_1)$  and  $(\mathbf{Q}_2, \varphi_2)$  be two weak solutions. Then

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 dx + \int_{\Omega} [L|\nabla\mathbf{Q}|^2 + (f'_{bulk}(\mathbf{Q}_1) - f'_{bulk}(\mathbf{Q}_2)) \cdot \mathbf{Q}] \\ & = \frac{1}{2} \epsilon_3 \int_{\Omega} \nabla\varphi \cdot (\nabla \cdot \mathbf{Q}) dx, \\ & \int_{\Omega} (\epsilon_0 \nabla\varphi) \cdot \nabla\varphi dx = -\epsilon_3 \int_{\Omega} (\nabla \cdot \mathbf{Q}) \cdot \nabla\varphi dx, \end{aligned}$$

where  $\mathbf{Q} = \mathbf{Q}_1 - \mathbf{Q}_2$ ,  $\varphi = \varphi_1 - \varphi_2$ . Plugging the second equation into the first one, we get

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int_{\Omega} |\mathbf{Q}|^2 dx + \int_{\Omega} \left( L|\nabla\mathbf{Q}|^2 + \frac{1}{2} \epsilon_0 |\nabla\varphi|^2 \right) dx \\ & = \int_{\Omega} [(f'_{bulk}(\mathbf{Q}_1) - f'_{bulk}(\mathbf{Q}_2)) \cdot \mathbf{Q}] dx \\ & \leq M \int_{\Omega} |\mathbf{Q}|^2 dx \text{ for some } M > 0. \end{aligned}$$



Hence  $\|\mathbf{Q}\|_{L^2} \leq \|Q(0)\|_{L^2} e^t = 0$  so that  $\mathbf{Q}_1 = \mathbf{Q}_2$  and  $\varphi_1 = \varphi_2$ . □

**THEOREM 3.3.** *If  $\mathbf{Q}_0 \in W^{1,2}(\Omega, \mathcal{S}_0)$ , then there is a subsequence of solutions to (1.4) which converges to a solution of the steady state problem as  $t \rightarrow \infty$ .*

*Proof.* Multiplying individual equation by  $\frac{\partial Q_{ij}}{\partial t}$  and integrating by parts followed by summing up, we obtain

$$\begin{aligned} \int_{\Omega} |\mathbf{Q}_t|^2 &= -\frac{d}{dt} \int_{\Omega} \left[ \frac{L}{2} |\nabla \mathbf{Q}|^2 + A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C (\operatorname{tr} \mathbf{Q}^2)^2 \right] dx \\ &\quad + \epsilon_3 \int_{\Omega} \nabla \cdot \mathbf{Q}_t \cdot \nabla \varphi \, dx - \frac{d}{dt} \int_{\Omega} |\nabla \varphi|^2 \, dx \\ &= \epsilon_3 \int_{\Omega} \nabla \cdot \mathbf{Q}_t \cdot \nabla \varphi \, dx. \end{aligned}$$

Then

$$\begin{aligned} &\int_{\Omega} |\mathbf{Q}_t|^2 \\ &= -\frac{d}{dt} \int_{\Omega} \left[ \frac{L}{2} |\nabla \mathbf{Q}|^2 + A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C (\operatorname{tr} \mathbf{Q}^2)^2 + |\nabla \varphi|^2 \right] dx \end{aligned}$$

and

$$\begin{aligned} &\int_0^T \int_{\Omega} |\mathbf{Q}_t|^2 \, dx \, dt \\ &= - \int_{\Omega} \left[ \frac{L}{2} |\nabla \mathbf{Q}|^2 + A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C (\operatorname{tr} \mathbf{Q}^2)^2 + |\nabla \varphi|^2 \right]_{t=T} \, dx \\ &\quad + \int_{\Omega} \left[ \frac{L}{2} |\nabla \mathbf{Q}|^2 + A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C (\operatorname{tr} \mathbf{Q}^2)^2 + |\nabla \varphi|^2 \right]_{t=0} \, dx \\ &\leq \int_{\Omega} \left[ \frac{L}{2} |\nabla \mathbf{Q}|^2 + A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C (\operatorname{tr} \mathbf{Q}^2)^2 + |\nabla \varphi|^2 \right]_{t=0} \, dx \\ &\quad + M|\Omega|, \end{aligned}$$

where  $M$  is the minimum value of  $A \operatorname{tr} \mathbf{Q}^2 - B \operatorname{tr} \mathbf{Q}^3 + C (\operatorname{tr} \mathbf{Q}^2)^2$ .

Hence we obtain  $\mathbf{Q}_t \in L^2(0, \infty; L^2(\Omega; \mathcal{S}_0))$ . This shows that

$$\int_{\Omega} |\mathbf{Q}_t(x, t_i)|^2 \, dx \rightarrow 0 \text{ as } i \rightarrow \infty,$$

for almost all sequence  $\{t_i\}_{i \in \mathbb{N}}$  satisfying  $t_i \rightarrow \infty$  as  $i \rightarrow \infty$ . Furthermore, we also get

$$(\nabla \mathbf{Q}, \nabla \varphi) \in L^\infty(0, \infty; L^2(\Omega; \mathcal{S}_0)) \times L^\infty(0, \infty; L^2(\Omega)).$$

By Poincaré inequality, we have

$$(\mathbf{Q}, \varphi) \in L^\infty(0, \infty; W^{1,2}(\Omega; \mathcal{S}_0)) \times L^\infty(0, \infty; W^{1,2}(\Omega))$$

and there is a sequence  $\{t_i\}_{i \in \mathbb{N}}$  with  $t_i \rightarrow \infty$  as  $i \rightarrow \infty$  such that

$$(\mathbf{Q}(x, t_i), \varphi(x, t_i)) \rightharpoonup (\bar{\mathbf{Q}}, \bar{\varphi}) \text{ weakly in } W^{1,2} \text{ as } t_i \rightarrow \infty.$$

Since  $(\mathbf{Q}, \varphi)$  is a weak solution pair,

$$\begin{cases} \left\langle \frac{\partial \mathbf{Q}}{\partial t}, \tilde{\mathbf{Q}} \right\rangle + \left\langle L \nabla \mathbf{Q} + A \mathbf{Q} - B \operatorname{tr} \mathbf{Q}^2 + C(\operatorname{tr} \mathbf{Q}^2) \mathbf{Q}, \nabla \tilde{\mathbf{Q}} \right\rangle \\ \quad + \epsilon \left\langle \nabla \varphi, \nabla \cdot \tilde{\mathbf{Q}} \right\rangle = 0, \\ \int_{\Omega} (\nabla \varphi \cdot \nabla \psi + \nabla \cdot \mathbf{Q} \cdot \nabla \psi) \, dx = 0, \end{cases}$$

for all  $\tilde{\mathbf{Q}} \in W^{1,2}(\Omega, \mathcal{S}_0)$ ,  $\psi \in W^{1,2}(\Omega)$ . Passing to the limit as  $t_i \rightarrow \infty$ , we obtain

$$\begin{cases} \int_{\Omega} (L \nabla \bar{\mathbf{Q}} + A \bar{\mathbf{Q}} - B \operatorname{tr} \bar{\mathbf{Q}}^2 + C(\operatorname{tr} \bar{\mathbf{Q}}^2) \bar{\mathbf{Q}}) \cdot \nabla \tilde{\mathbf{Q}} \\ \quad + \epsilon \int_{\Omega} \nabla \bar{\varphi} \cdot (\nabla \cdot \tilde{\mathbf{Q}}) \, dx = 0, \\ \int_{\Omega} (\nabla \bar{\varphi} \cdot \nabla \psi + \nabla \cdot \bar{\mathbf{Q}} \cdot \nabla \psi) \, dx = 0. \end{cases}$$

This completes the proof.  $\square$

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Department of Mathematics  
 Chungnam National University  
 Daejeon 305-764, Republic of Korea  
 E-mail: jhpark2003@gmail.com